

# A method of verified computations for nonlinear parabolic equations

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Joint with

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# Nonlinear parabolic equations

Let  $\Omega$  be a bounded polygonal domain in  $\mathbb{R}^2$ .

$$(P) \quad \begin{cases} \partial_t u + Au = f(u) & \text{in } (0, \infty) \times \Omega, \\ u(t, x) = 0 & \text{on } (0, \infty) \times \partial\Omega, \\ u(0, x) = u_0(x) & \text{in } \Omega, \end{cases}$$

- ▶  $\partial_t u = \frac{du}{dt}$ ,
- ▶  $f$  : a twice Fréchet differentiable nonlinear mapping,
- ▶  $u_0 \in H_0^1(\Omega)$  is a given initial function,
- ▶  $A : D(A) \subset H_0^1(\Omega) \rightarrow L^2(\Omega)$ , self-adjoint.

$L^p(\Omega)$ : the set of  $L^p$ -functions,

$H^1(\Omega)$ : the first order Sobolev space of  $L^2(\Omega)$ ,

$H_0^1(\Omega) := \{u \in H^1(\Omega) : u = 0 \text{ on } \partial\Omega\}$ .

## Differential operator $A$

We set

$$A := - \sum_{1 \leq i, j \leq 2} \frac{\partial}{\partial x_j} \left( a_{ij}(x) \frac{\partial}{\partial x_i} \right),$$

where  $a_{ij}(x) (= a_{ji}(x))$  is in  $W^{1,\infty}(\Omega)$  and satisfies

$$\sum_{1 \leq i, j \leq 2} a_{ij}(x) \xi_i \xi_j \geq \mu |\xi|^2, \quad \forall x \in \Omega, \quad \forall \xi \in \mathbb{R}^2 \text{ with } \mu > 0.$$

$a : H_0^1(\Omega) \times H_0^1(\Omega) \rightarrow \mathbb{R}$  is a bilinear form:

$$a(u, v) := \sum_{1 \leq i, j \leq 2} \left( a_{ij}(x) \frac{\partial u}{\partial x_i}, \frac{\partial v}{\partial x_j} \right)_{L^2}$$

satisfying

$$a(u, u) \geq \mu \|u\|_{H_0^1}^2, \quad |a(u, v)| \leq M \|u\|_{H_0^1} \|v\|_{H_0^1}, \quad \forall u, v \in H_0^1(\Omega).$$

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## Weak solutions (aim of this study)

The weak form of  $(P)$ :

find  $u(t) := u(t, \cdot) \in H_0^1(\Omega)$  for  $t > 0$  s.t.

$$(\partial_t u(t), v)_{L^2} + a(u(t), v) = (f(u(t)), v)_{L^2}, \quad \forall v \in H_0^1(\Omega).$$

Let  $T := (0, t']$  for a fixed  $0 < t' < \infty$ .

We seek a weak solution in the Banach space  $L^\infty(T; H_0^1(\Omega))$  with the norm:

$$\|u\|_{L^\infty(T; H_0^1(\Omega))} := \operatorname{ess\,sup}_{t \in T} \|u(t)\|_{H_0^1}.$$

Then, we enclose the weak solution in a neighborhood of a numerical solution.

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## Previous studies

[1] M.T. Nakao, T. Kinoshita and T. Kimura,

*“On a posteriori estimates of inverse operators for linear parabolic initial-boundary value problems”*, Computing 94(2-4), 151–162, 2012.

[2] M.T. Nakao, T. Kimura and T. Kinoshita,

*“Constructive A Priori Error Estimates for a Full Discrete Approximation of the Heat Equation”*, Siam J. Numer. Anal., 51(3), 1525–1541, 2013.

[3] T. Kinoshita, T. Kimura and M.T. Nakao,

*“On the a posteriori estimates for inverse operators of linear parabolic equations with applications to the numerical enclosure of solutions for nonlinear problems”*, Numer. Math, 126(4), 679–701, 2014. Online First, 2013.

## Features & Comparison

- ▶ The enclosure of weak solutions is a ball of

$$L^2(J; H_0^1(\Omega)) := \left\{ u(t) \in H_0^1(\Omega) : \int_J \|u(t)\|_{H_0^1}^2 dt < \infty \right\}.$$

- ▶ Use the full discretization projection  $P_h^k$  cleverly;

$$\|u - P_h^k u\|_{L^2(J; H_0^1(\Omega))} \leq C(h, k) \|(\partial_t - \Delta)u\|_{L^2(J; L^2(\Omega))}$$

$$\text{for } \forall u \in H^1(J; L^2(\Omega)) \cap L^2(J; D(\Delta)).$$

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- ▶ **Analitic semigroup**  $e^{-t\mathcal{A}}$  generated by  $-\mathcal{A}^1$ .

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<sup>1</sup> $\mathcal{A} : H_0^1(\Omega) \rightarrow H^{-1}(\Omega)$  s.t.  $\langle \mathcal{A}u, v \rangle := a(u, v)$ ,  $\forall v \in H_0^1(\Omega)$ .

## Semigroup theory

It is fact that the weak form of  $A$ , which is denoted by  $-\mathcal{A}$ , generates the analytic semigroup  $\{e^{-t\mathcal{A}}\}_{t \geq 0}$  over  $H^{-1}(\Omega)$ . The following abstract problem has an unique solution:

$$\partial_t u + \mathcal{A}u = 0, \quad u(0, x) = u_0 \implies \exists u = e^{-t\mathcal{A}}u_0.$$

Fact

Let  $x \in D(\mathcal{A})$  and  $\lambda_0$  be a positive number.  $\mathcal{A}$  satisfies

$$\langle -\mathcal{A}x, x \rangle \leq 0, \quad R(\lambda_0 I + \mathcal{A}) = H^{-1}(\Omega).$$

Then, there exists an analytic semigroup  $\{e^{-t\mathcal{A}}\}_{t \geq 0}$  generated by  $-\mathcal{A}$ .

Proofs are found in several textbooks.

## Two-steps procedure

1. Check a sufficient condition for proving existence and local uniqueness of the weak solution in a time interval  $J := (t_0, t_1]$  ( $0 \leq t_0 < t_1 < \infty$ ).

If it succeeds, then the weak solution is in the ball<sup>2</sup>

$$B(\omega, \rho) := \left\{ y \in L^\infty(J; H_0^1(\Omega)) : \|y - \omega\|_{L^\infty(J; H_0^1(\Omega))} \leq \rho \right\}.$$

2. Connect each enclosure of the weak solution by iterating numerical verification. Extend a time interval in which existence of the weak solution is guaranteed.

We call this 2nd step “*concatenation scheme*”.

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# 1. Verification theorem

## Considered problem

$J = (t_0, t_1]$  : arbitrary time interval.  $\tau := t_1 - t_0$ .

$$(P_J) \begin{cases} \partial_t u + Au = f(u) & \text{in } J \times \Omega, \\ u(t, x) = 0 & \text{on } J \times \partial\Omega, \\ u(t_0, x) = \zeta(x) & \text{in } \Omega, \end{cases}$$

where  $\zeta$  is an initial function in  $H_0^1(\Omega)$ .

$V_n \subset H_0^1(\Omega)$  : a finite dimensional subspace.

Starts from:  $\hat{v}_0, \hat{v}_1 \in V_n$ .

$$w(t) = \hat{v}_0 \phi_0(t) + \hat{v}_1 \phi_1(t), \quad t \in J,$$

where  $\phi_k(t)$  is a linear Lagrange basis:  $\phi_k(t_j) = \delta_{kj}$  ( $\delta_{kj}$  is a Kronecker's delta).

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$V_h \subset H_0^1(\Omega)$  : a finite dimensional subspace.

Starts from:  $\hat{u}_0, \hat{u}_1 \in V_h$

$$\omega(t) = \hat{u}_0 \phi_0(t) + \hat{u}_1 \phi_1(t), \quad t \in J,$$

where  $\phi_k(t)$  is a linear Lagrange basis:  $\phi_k(t_j) = \delta_{kj}$  ( $\delta_{kj}$  is a Kronecker's delta).

### Theorem (Verification theorem)

Suppose that  $\zeta$  is in the  $\varepsilon_0$ -neighborhood of  $\hat{u}_0$ ;  $\delta$  satisfies

$$\left\| \int_{t_0}^t e^{-(t-s)\mathcal{A}} (\partial_t \omega(s) + \mathcal{A}\omega(s) - f(\omega(s))) ds \right\|_{L^\infty(J; H_0^1(\Omega))} \leq \delta$$

and a local Lipschitz bound  $L_{\rho_0} > 0$  for  $\rho \geq \rho_0 > 0$  satisfies

$$\|f(\varphi) - f(\psi)\|_{L^\infty(J; L^2(\Omega))} \leq L_{\rho_0} \|\varphi - \psi\|_{L^\infty(J; H_0^1(\Omega))},$$

where  $\forall \varphi, \psi \in B(\omega, \rho)$ . If there exists  $\rho > 0$  such that

$$\frac{M}{\mu} \varepsilon_0 + \frac{2}{\mu} \sqrt{\frac{M\tau}{e}} L_{\rho} \rho + \delta < \rho,$$

then the weak solution  $u(t)$ ,  $t \in J$  of  $(P_J)$  uniquely exists in the ball  $B(\omega, \rho)$ .

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## Sketch of proof

Let  $z(t) \in H_0^1(\Omega)$  for a fixed  $t \in J$ . We put  $u(t) = \omega(t) + z(t)$ .  
For any  $v \in H_0^1(\Omega)$ ,

$$\begin{aligned} & (\partial_t z(t), v)_{L^2} + a(z(t), v) \\ &= (f(u(t)), v)_{L^2} - ((\partial_t \omega(t), v)_{L^2} + \langle \mathcal{A}\omega(t), v \rangle) \\ &= \langle g(z(t)), v \rangle, \end{aligned}$$

where  $g(z(t)) = f(u(t)) - (\partial_t \omega(t) + \mathcal{A}\omega(t)) \in H^{-1}(\Omega)$ .

Define  $S : L^\infty(J; H_0^1(\Omega)) \rightarrow L^\infty(J; H_0^1(\Omega))$  with the analytic semigroup  $e^{-t\mathcal{A}}$  by

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$$S(z) := e^{-(t-t_0)\mathcal{A}}(\zeta - \hat{u}_0) + \int_{t_0}^t e^{-(t-s)\mathcal{A}} g(z(s)) ds.$$

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For  $\rho > 0$ , let  $Z := \left\{ z \in L^\infty(J; H_0^1(\Omega)) : \|z\|_{L^\infty(J; H_0^1(\Omega))} \leq \rho \right\}$ .

On the basis of Banach's fixed-point theorem, we show a sufficient condition of  $S$  having a fixed-point in  $Z$ .

Then it follows

$$\|S(z)\|_{L^\infty(J; H_0^1(\Omega))} \leq \frac{M}{\mu} \varepsilon_0 + \frac{2}{\mu} \sqrt{\frac{M\tau}{c}} L_f \rho + \delta.$$

$\|S(z)\|_{L^\infty(J; H_0^1(\Omega))} < \rho$  holds from the condition of the theorem. It implies that  $S(z) \in Z$ .

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If  $z_1, z_2$  in  $Z$ ,

$$\|S(z_1) - S(z_2)\|_{L^\infty(J; H_0^1(\Omega))} \leq \frac{2}{\mu} \sqrt{\frac{M\tau}{e}} L(\rho) \|z_1 - z_2\|_{L^\infty(T_k; H_0^1(\Omega))}$$

holds. The condition of theorem also implies

$$\frac{2}{\mu} \sqrt{\frac{M\tau}{e}} L(\rho) < 1.$$

Therefore,  $S$  becomes a contraction mapping.

Banach's fixed-point theorem yields that there uniquely exists a fixed-point of  $S$  in  $Z$ .

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Therefore,  $S$  becomes a contraction mapping.

Banach's fixed-point theorem yields that there uniquely exists a fixed-point of  $S$  in  $Z$ .

**Theorem** (A posteriori error estimate)

Suppose that the weak solution  $u(t)$ ,  $t \in J$ , of  $(P_J)$  is in  $B(\omega, \rho)$ . Assuming that  $\tilde{\delta} > 0$  satisfies

$$\left\| \int_{t_0}^{t_1} e^{-(t_1-s)\mathcal{A}} (\partial_t \omega(s) + \mathcal{A}\omega(s) - f(\omega(s))) ds \right\|_{H_0^1} \leq \tilde{\delta}.$$

Then, the following a posteriori error estimate holds:

$$\|u(t_1) - \hat{u}_1\|_{H_0^1} \leq \frac{M}{\mu} e^{-\tau\lambda_{\min}} \varepsilon_0 + \frac{2}{\mu} \sqrt{\frac{M\tau}{e}} L_\rho \rho + \tilde{\delta} =: \varepsilon_1.$$

## 2. Concatenation scheme

## Considered problem

Let  $T = (0, t']$  for  $t' > 0$ . We divide  $T$  into  $n$  intervals by  $0 = t_0 < t_1 < \dots < t_n = t'$  for  $n \in \mathbb{N}$ .

Define  $T_k := (t_{k-1}, t_k]$  and  $\tau_k := t_k - t_{k-1}$  ( $k = 1, 2, \dots, n$ ).

$$(P_T) \begin{cases} \partial_t u + Au = f(u) & \text{in } T \times \Omega, \\ u(t, x) = 0 & \text{on } T \times \partial\Omega, \\ u(t_0, x) = u_0(x) & \text{in } \Omega, \end{cases}$$

where  $u_0 \in L^2(\Omega)$  is a given initial function.

From  $\hat{u}_k \in V_h$ , we construct a numerical solution  $\omega(t)$  by

$$\omega(t) := \sum_{k=0}^n \hat{u}_k \phi_k(t), \quad t \in T,$$

where  $\phi_k(t)$  is a piecewise linear Lagrange basis.

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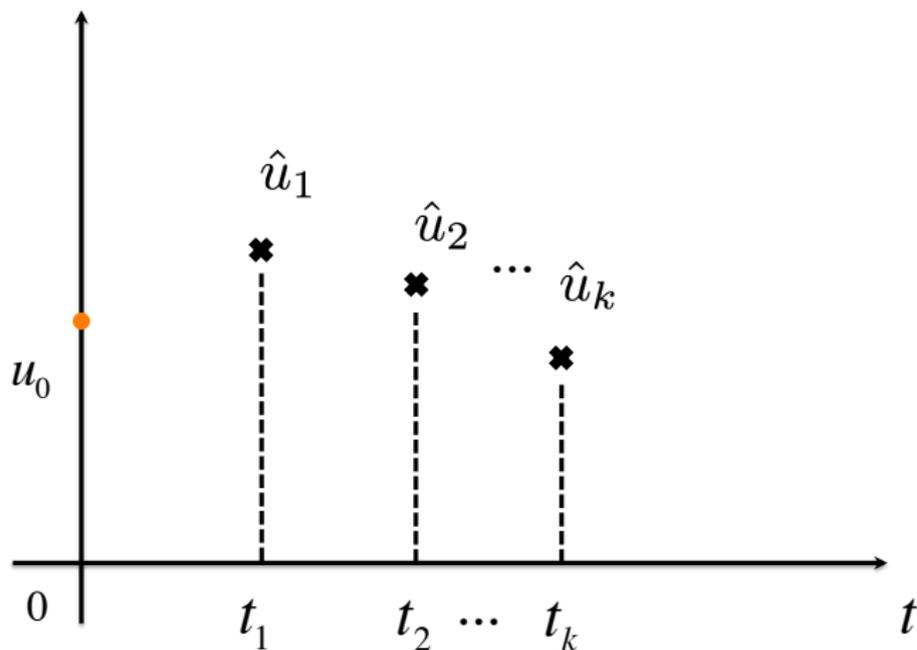
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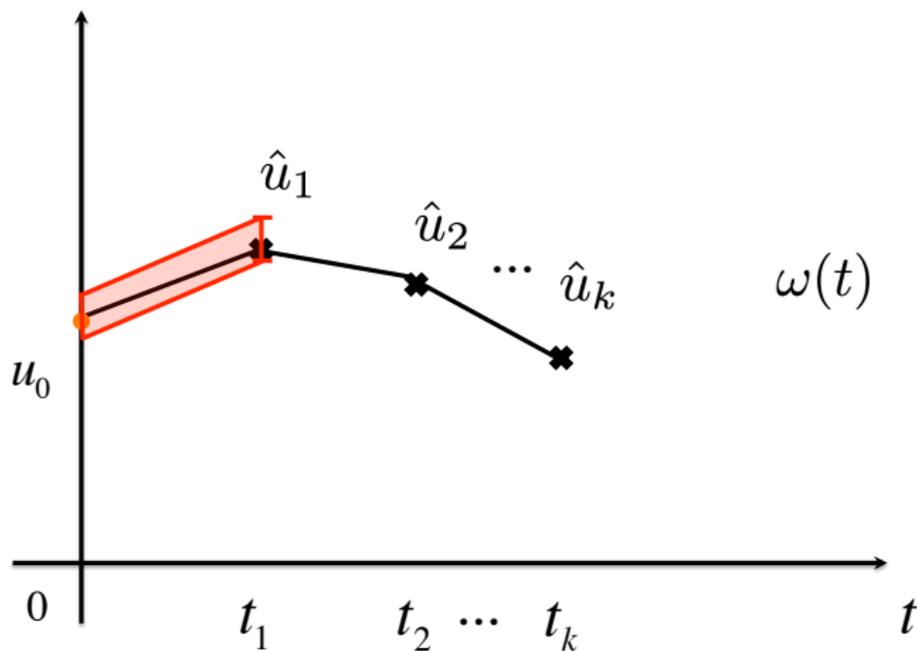
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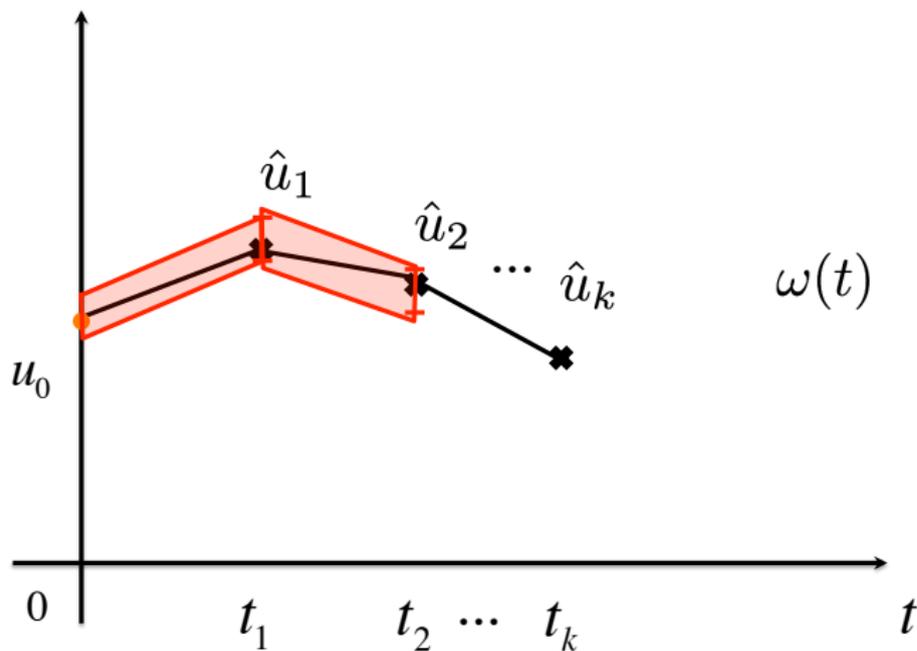
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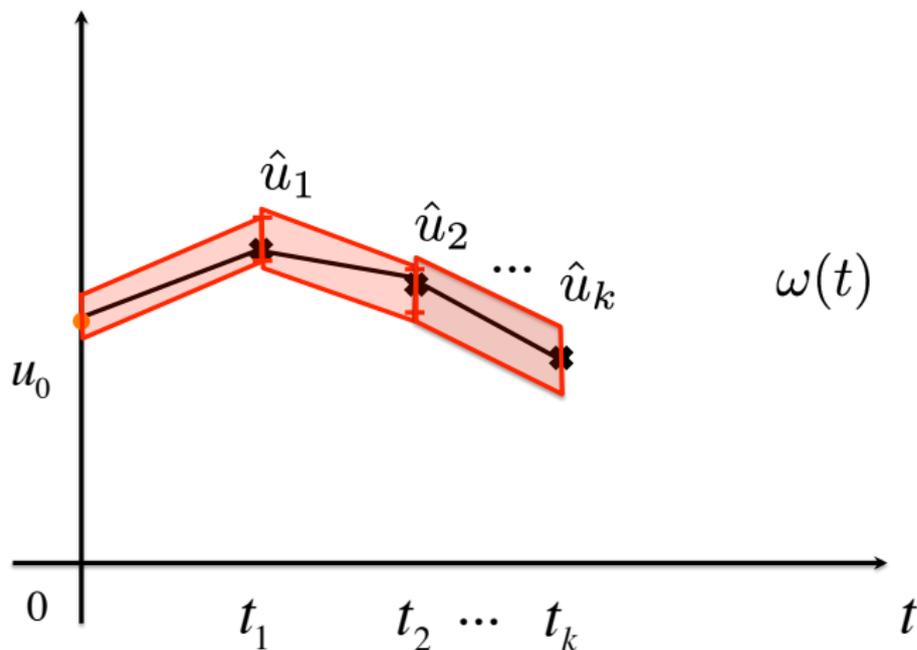
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# Computational example

## Fujita-type parabolic problem

Let  $\Omega := (0, 1)^2$  be an unit square domain in  $\mathbb{R}^2$ .

$$(F) \quad \begin{cases} \partial_t u - \Delta u = u^2 & \text{in } (0, \infty) \times \Omega, \\ u(t, x) = 0 & \text{on } (0, \infty) \times \partial\Omega, \\ u(0, x) = u_0(x) & \text{in } \Omega, \end{cases}$$

Let  $\gamma > 0$  be an parameter of the initial function:

$$u_0(x) = \gamma x_1(1 - x_1)x_2(1 - x_2).$$

$\mathcal{V}_h$ : the quadratic conforming finite elements ( $P_2$ -elements).

$h$ : a spatial mesh size;

the backward Euler method is employed

with time step

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## Computational results

Table:  $\|u(t_k) - \hat{u}_k\|_{H_0^1} \leq \varepsilon_k$ ,  $\|u - \omega\|_{L^\infty(T_k; H_0^1(\Omega))} \leq \rho_k$  when  
 $h = 2^{-4}$ ,  $\tau = 2^{-8}$ , and  $\gamma = 1$ .

$T_k = (t_{k-1}, t_k]$	$\varepsilon_k$	$\rho_k$
(0,0.0039062]	0.020155	0.037646
(0.0039062,0.0078125]	0.030051	0.041554
(0.0078125,0.011719]	0.038089	0.049313
(0.011719,0.015625]	0.044657	0.055699
(0.015625,0.019531]	0.050001	0.060873
$\vdots$	$\vdots$	$\vdots$
(0.48047,0.48438]	0.00013041	0.00014184
(0.48438,0.48828]	0.00012186	0.00013255
(0.48828,0.49219]	0.00011388	0.00012386
(0.49219,0.49609]	0.00010641	0.00011573
(0.49609,0.5]	9.9431E-5	0.00010813

# Computational results

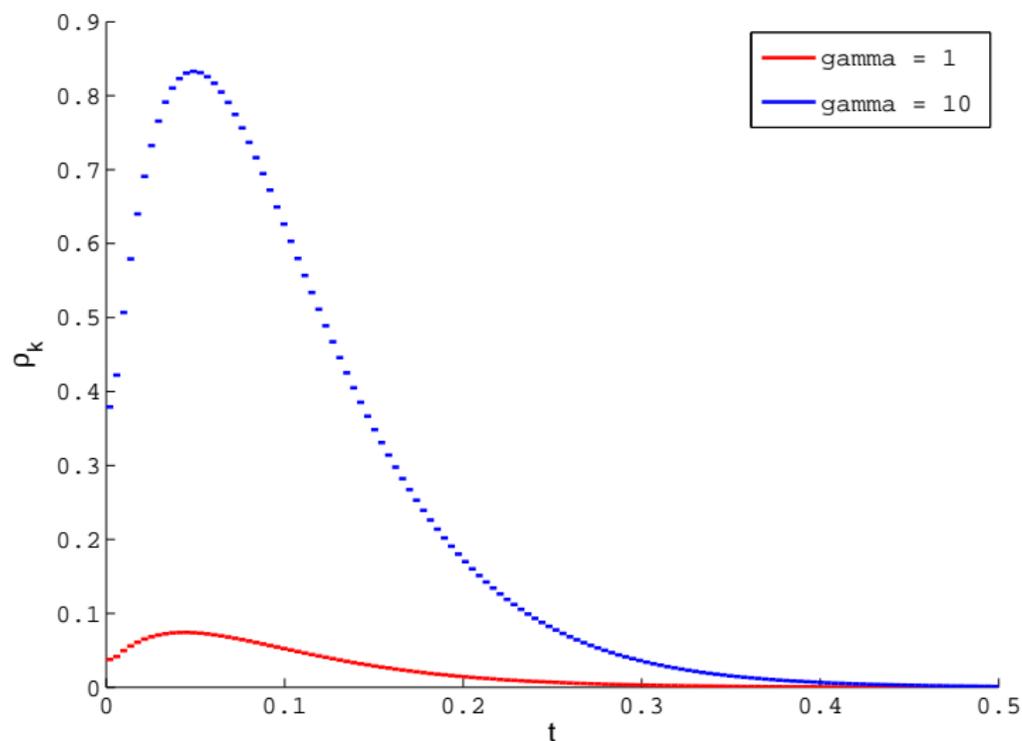


Figure:  $h = 2^{-4}$ ,  $\tau = 2^{-8}$ ,  $\gamma = 1, 10$ .

# Computational results

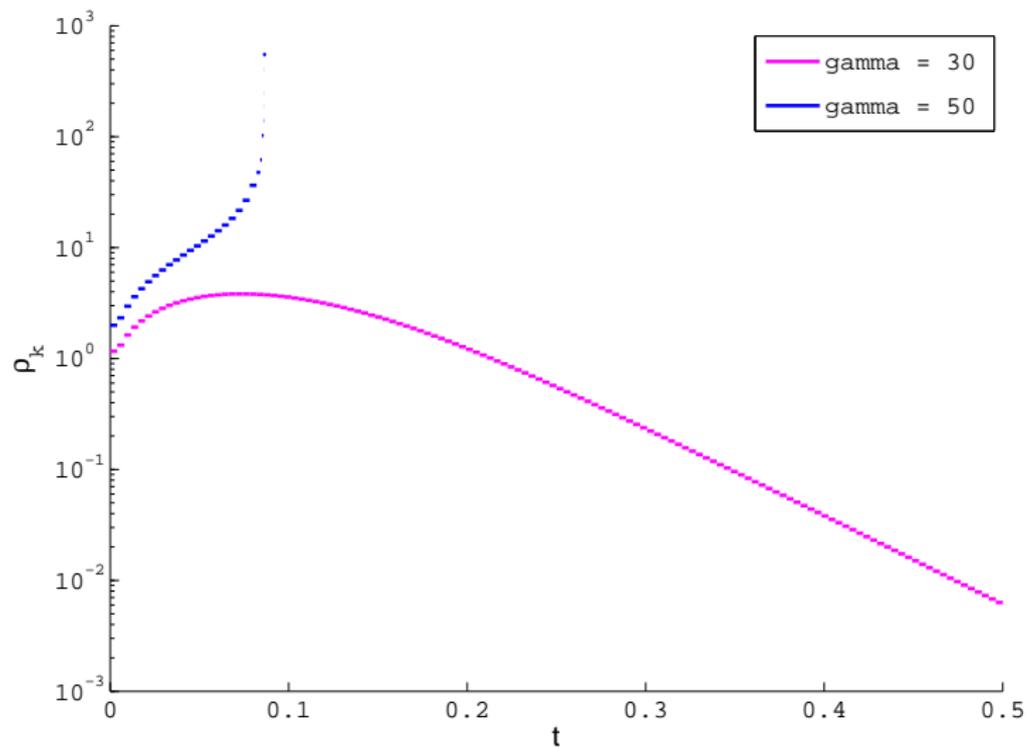


Figure:  $h = 2^{-4}$ ,  $\tau = 2^{-8}$ ,  $\gamma = 30, 50$ .

## Conclusion

- ▶ Enclose the weak solution of parabolic problems
- ▶ Verification theorem
- ▶ Concatenation scheme of a verified inclusion

## Further works

- ▶ Shape error estimate is desired.
- ▶ How about strong solution?

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## Collaborators of this study

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Thank you for kind attention!