

SONIC

A Solver and Optimizer for Nonlinear Problems
based on Interval Computations

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What is SONIC

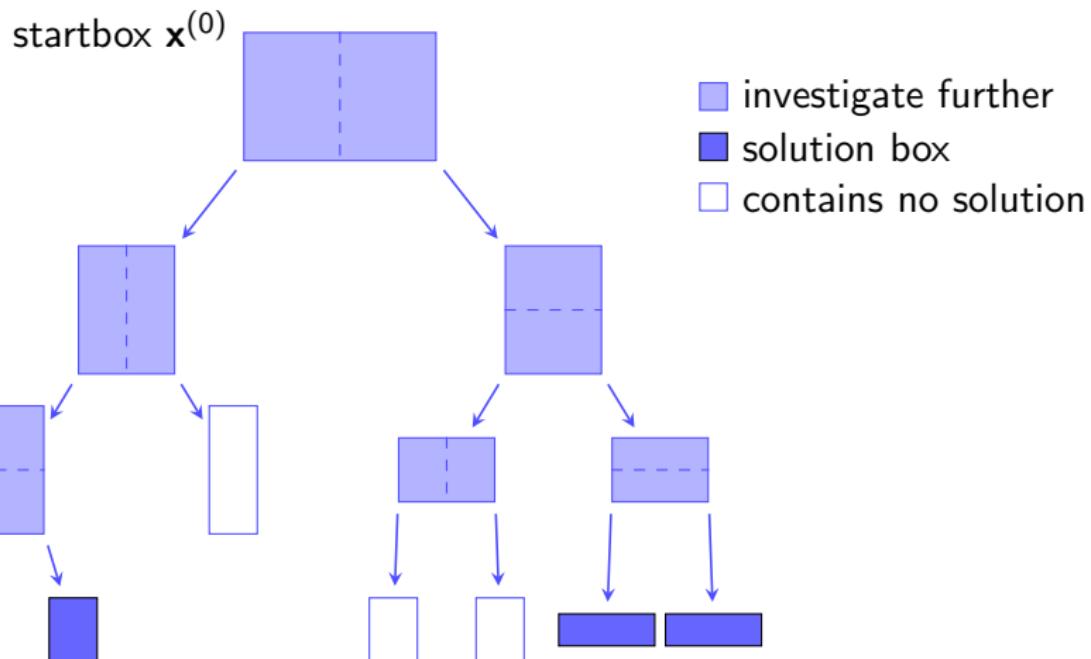
SONIC – A **S**olver and **O**ptimizer for **N**onlinear **P**roblems
based on **I**nterval **C**omputations

- rigorous solver for nonlinear systems
- developed at RWTH Aachen and University of Wuppertal
- initially for dynamic systems in chemical processes

Features

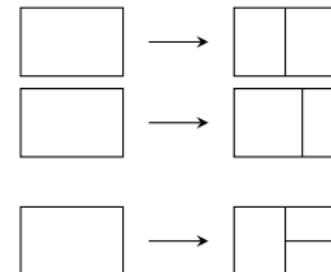
- written in C++
- portability and performance by different interval libraries:
choice between C-XSC, filib++
- parallel versions for distributed and shared memory
(MPI, OpenMP)
- solver for optimization problems
- handling of unbounded intervals

Branch and Bound



Subdivision

- subdivision using gaps caused by division
- choice of subdivision direction:
 - subdivide direction with largest width
 - search zeros near boundary
 - search direction with highest influence on function value
 - hybrid strategy
- choice of subdivision point:
 - bisect at midpoint
 - shift bisection point
- iterated subdivision



Contractors

Aim: Contract or discard a given box

- Constraint propagation
- Taylor refinement
- Interval Newton method
- Taylor models

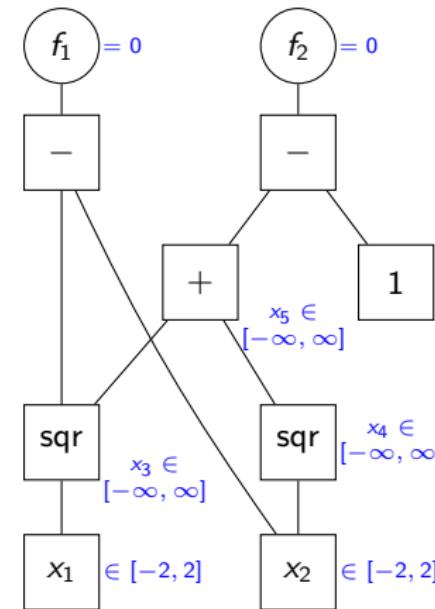
Constraint propagation

Consider system

$$f_1(x) = x_1^2 - x_2 = 0$$

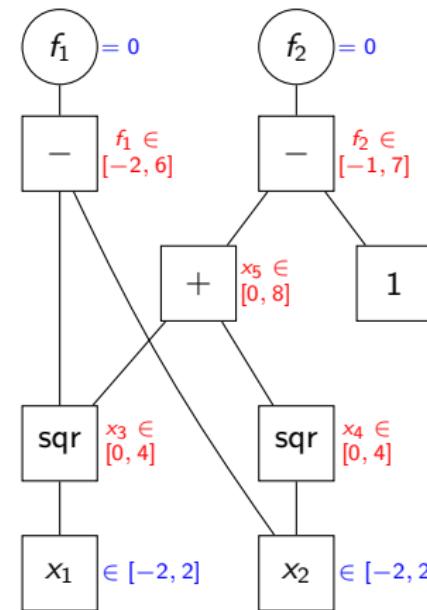
$$f_2(x) = x_1^2 + x_2^2 - 1 = 0$$

with $x \in [-2, 2]^2$



Constraint propagation

Forward sweep corresponds to the natural interval evaluation

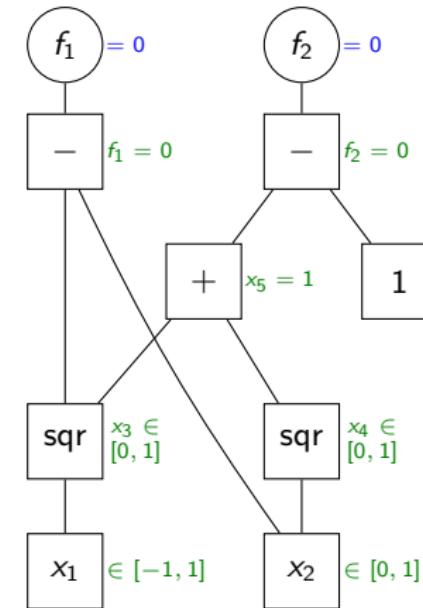


Constraint propagation

Backward sweep yields narrower bounds:

$$\begin{aligned}
 0 &= f_1 = x_3 - x_2 \\
 \Leftrightarrow x_3 &= f_1 + x_2 \in \\
 (0 + [-2, 2]) \cap [0, 4] &= [0, 2]
 \end{aligned}$$

$$\begin{aligned}
 &\dots \\
 x_1 &= \pm\sqrt{x_3} \in [-1, 1] \\
 x_2 &= \pm\sqrt{x_4} \in [0, 1]
 \end{aligned}$$



Taylor refinement

Gain sharper enclosure by Taylor expansion for $f : \mathcal{D} \subseteq \mathbb{R}^n \rightarrow \mathbb{R}$:

$$f(\mathbf{x}) \subseteq f(\mathbf{c}) + \sum_{i=1}^n \mathbf{s}_i \cdot (\mathbf{x}_i - c_i)$$

$$\mathbf{x}'_i := \mathbf{x}_i \cap \left(c_i - \left(f(\mathbf{c}) + \sum_{\substack{j=1 \\ j \neq i}}^n \mathbf{s}_j \cdot (\mathbf{x}_j - c_j) \right) \oslash \mathbf{s}_i \right), \quad i = 1 \dots n$$

with some center $\mathbf{c} \in x$ and slope vector \mathbf{s}

Interval Newton method

Refines or discards box

$$\mathbf{f}(\mathbf{x}) \subseteq f(c) + \mathbf{S}(\mathbf{x} - c)$$

$$-f(c) = \mathbf{S}(x^* - c)$$

- solve with Gauß-Seidel-approach
- several preconditioners available
- can be used to verify the existence of a (unique) solution

Algorithm 1 Application scheme for contractors (box x)

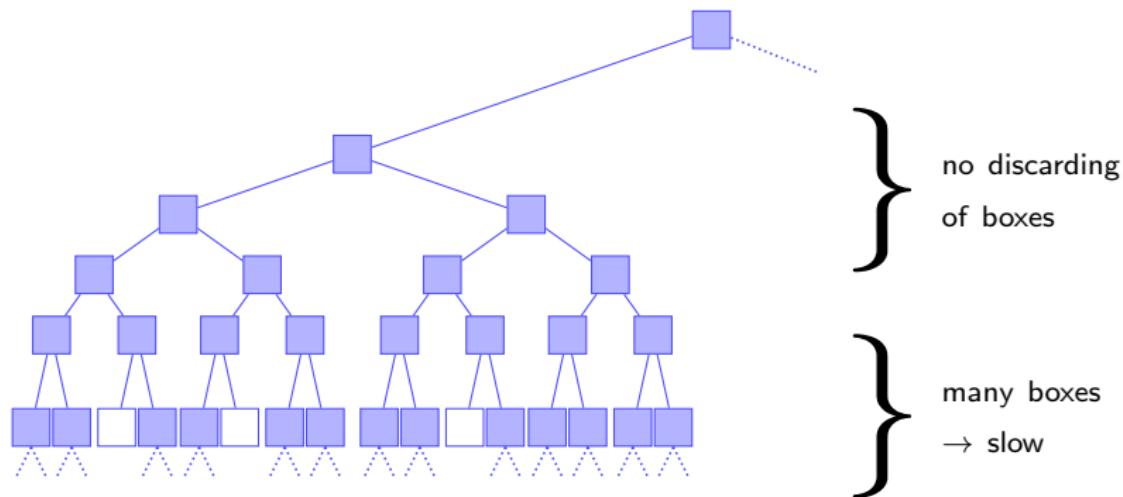
```
1: if CP is enabled then apply CP
2: if  $x$  cannot contain a solution then discard  $x$ 
3: if Taylor refinement of first order is enabled then
4:   apply Taylor refinement of first order
5:   if CP is enabled then apply CP
6: end if
7: if  $x$  cannot contain a solution then discard  $x$ 
8: if Taylor refinement of second order is enabled then
9:   apply Taylor refinement of second order
10:  if CP is enabled then apply CP
11: end if
12: if  $x$  cannot contain a solution then discard  $x$ 
13: if Newton method is enabled then
14:   apply Newton method
15:   if CP is enabled then apply CP
16: end if
17: if  $x$  cannot contain a solution then discard  $x$ 
```

Verification

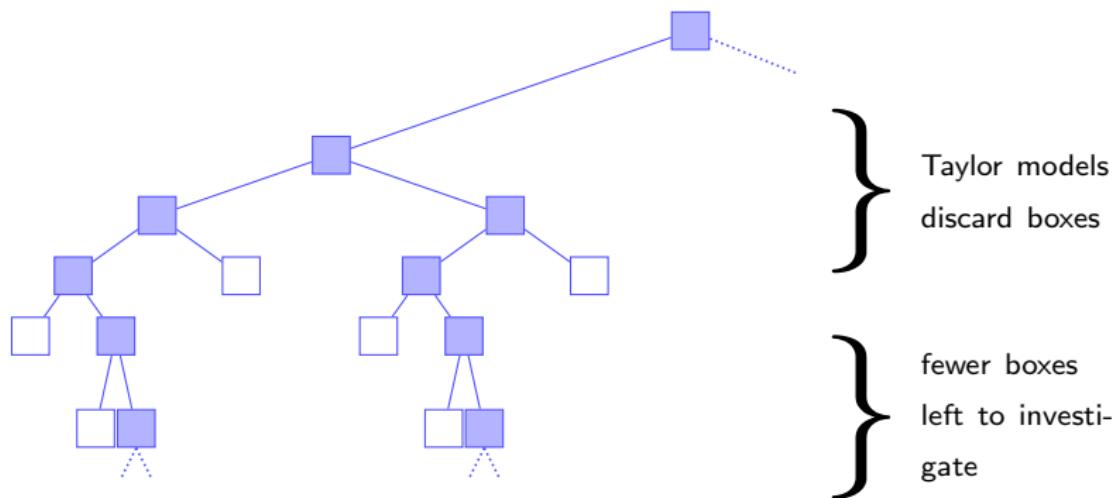
Aim: Prove existence or uniqueness of a solution in a given box

- Newton test
 - apply one step of the interval Newton method
 - proofs uniqueness
- Miranda test
 - compare sign of function values on opposite facets
- Borsuk test
- topological degree test

Problem: Too many boxes...



Problem: Too many boxes...



Taylor models

Idea: Enclosure of a function over its course

based on the works by Berz, Hoefkens and Makino

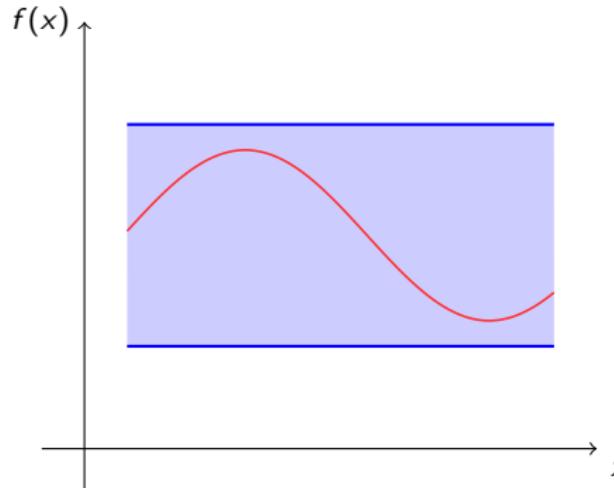
Consists of

- domain $\mathcal{D} \in \mathbb{R}^v$
- reference point $x_0 \in \mathcal{D}$
- Taylor polynomial $P_n : \mathcal{D} \rightarrow \mathbb{R}^w$ of order n
- remainder interval $R \in \mathbb{IR}^w$

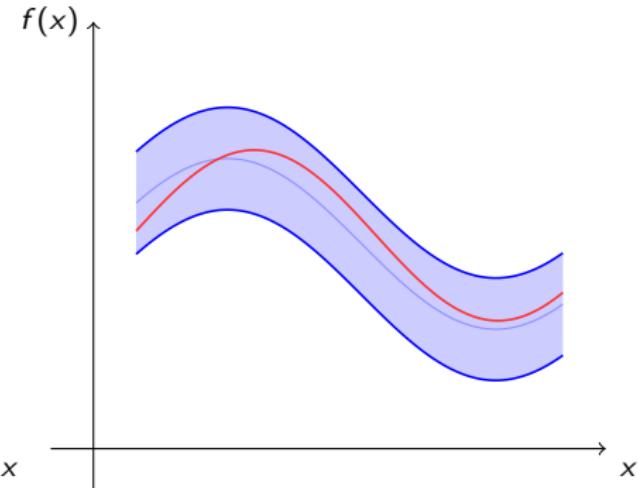
Inclusion property for all $x \in \mathcal{D}$:

$$f(x) \in P_n(x) + R$$

Function enclosures



Enclosure by a box ...



... and a Taylor Model

Properties of Taylor models

- sharper enclosure over relatively large domain
⇒ avoids subdivisions
- the remainder interval scales with the $(n + 1)$ -st order of the magnitude of \mathcal{D}
- reduced impact of the dependency problem
- number of coefficients for a polynomial of order n with v variables: $\frac{(n+v)!}{n! \cdot v!}$

Taylor models in SONIC

Usage of Taylor models as a contractor in SONIC:

Algorithm 2 Usage of Taylor models as a contractor (box x)

- 1: build Taylor model T over x
- 2: compute evaluation $B(T)$ of T
- 3: **if** $0 \notin B(T)$ **then**
- 4: discard x
- 5: **end if**

Results

Observations for the naive usage of Taylor models:

- computation time increases significantly
- most time is consumed on the buildup of the TM
- very few boxes get discarded
- natural function evaluation of Taylor polynomial causes overestimations
→ linear dominated bounder

Inverse Taylor models

Taylor models $T = (P_n, x_0, \mathcal{D}, R)$ and $S = (G_n, y_0, \Delta, \Omega)$

S left-inverse Taylor model for T if

- $G_n \circ P_n =_n \mathcal{I}$
- $P_n(x_0) = y_0$
- $f \in T \Rightarrow f(\mathcal{D}) \subset \Delta$
- $B(G_n(T) - I) \subsetneq \Omega$

Theorem

Let $T = (P_n, x_0, \mathcal{D}, R)$ and $S = (G_n, y_0, \Delta, \Omega)$ be given Taylor models such that S is a left-inverse Taylor model for T . Assume that $f \in T$ is invertible over \mathcal{D} .

Then there is $g \in S$ such that $g = f^{-1}$ on $f(\mathcal{D})$.

Newton method with inverse Taylor models

Algorithm 3 Newton method with taylor models ()

- 1: $k := 0$
- 2: **repeat**
- 3: build n -th order Taylor model $T^{(k)}$
 over $D^{(k)}$ with reference point $mid(D^{(k)})$
- 4: compute left-inverse Taylor model $S^{(k)}$ for $T^{(k)}$
- 5: $D^{(k+1)} := D^{(k)} \cap S^{(k)}(0)$
- 6: **if** $D^{(k+1)} = \emptyset$ **then**
- 7: discard box
- 8: **end if**
- 9: $k := k + 1$
- 10: **until** $D^{(k)}$ accurate enough

Properties

Properties of the inverse TM Newton method:

- faster speed of convergence
- larger domain of convergence
- less domain splitting required
- less impact of dependency problem and cancellation errors

Future plans

- web interface
- graphical output

Contact

For questions write to

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